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Formalized Data Flow Diagrams and Their Relation to Other Computational Models

Jürgen Symanzik and Albert L. Baker

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1 FORMALIZED DATA FLOW DIAGRAMS AND THEIR RELATION TO OTHER COMPUTATIONAL MODELS

Abstract

One approach to the formalization of Data Flow Diagrams (DFD's) is presented by Coleman ([Col91], [CB94]) and Leavens, et al., [IWBL96]. These Formalized Data Flow Diagrams (FDFD's) can be viewed as another model of computation. This paper contains an analysis of the computational power of these FDFD's. We first consider the issue whether certain features of FDFD's affect their computational power. A Reduced Data Flow Diagram (RDFD) is an FDFD with no stores, finite domains for flow values, and no facility for testing for empty flows, but it may contain persistent flows. An RDFD without persistent flows is called a persistent flow-free Reduced Data Flow Diagram (PFF-RDFD). We show that PFF-RDFD's are Turing equivalent. The other features of FDFD's only add to the expressive power of FDFD's ([SB96]). Therefore, any FDFD can be expressed as an PFF-RDFD. Our proof that PFF-RDFD's are Turing equivalent proceeds as follows. We first show that any RDFD can be simulated by a FIFO Petri Net. We then show that any Program Machine can be simulated by an PFF-RDFD. It is known that FIFO Petri Nets and Program Machines both are Turing equivalent.
1.1 Introduction

Traditional Data Flow Diagrams (DFD's) are the cornerstone of the software development methodology known as “Structured Analysis” (SA) ([DeM78], [WM85a]), and they are probably the most widely used specification technique in industry today ([BB93]). DFD's are popular because of their graphical representation and their hierarchical structure. Thus, they are ideally suited for users with non-technical backgrounds and are commonly used to depict the static structure of information flow in a system.

Traditional DFD's consist of a set of bubbles and a set of labeled flows. Bubbles represent either processes in a concurrent system or sequential procedures and are usually drawn as circles, ovals, or boxes. Flows represent data paths and are drawn as arrows connecting the bubbles. Flows coming into a bubble are called inflows and flows leaving a bubble are called outflows. Informally, a bubble reads the information on its inflows, and produces new information on its outflows. There are two types of flows. Persistent flows are like shared variables whose values are written by the source bubble and read by the destination bubble. Consumable flows are modelled as unbounded FIFO queues, with the source bubble enqueuing values on the queue and the destination bubble dequeuing values.

Even though traditional DFD's are popular, they lack formality and do not provide a rigorous definition of system functionality. Numerous attempts to formalize DFD's have appeared in the technical literature, e.g., in [DeM78], [WM85a], [WM85b], [Har87], [TP89], [You89], [Har92], and [Har96]. We focus on the Formalized Data Flow Diagrams (FDFD's) developed by Coleman, Wahls, Baker, and Leavens in [Col91], [CB94], [WBL93], and [IWB96]. We answer the following questions about the computational power of FDFD's. Do FDFD's have the same computational power as FIFO Petri Nets, another specification technique for concurrent and distributed systems? If so, to which class of FIFO Petri Nets are FDFD's equivalent? Are FDFD's Turing equivalent?

After definitions of FDFD's, Reduced Data Flow Diagrams (RDFD's), persistent flow-free RDFD's (PFF-RDFD's), FIFO Petri Nets, and Program Machines are given in Section 1.2, we answer the above questions in Section 1.3. Indeed, we will show that PFF-RDFD's and Turing Machines are equivalent. Actually, we will not directly compare PFF-RDFD's and Turing Machines, but instead provide simulations of RDFD's by FIFO Petri Nets and simulations of Program Machines by PFF-RDFD's. A summary and a preview of future work concludes this paper in Section 1.4.
1.2 Computational Models

In this section we define FDFD's, RDFD's, and PFF-RDFD's, summarize the definitions of FIFO Petri Nets and Program Machines, and introduce the overall concept of a Computation System.

1.2.1 FDFD's and RDFD's

We will use the formal definitions from [LWBL96] to introduce Formalized Data Flow Diagrams (FDFD's). The cited paper contains a more detailed explanation of the underlying operational semantics of FDFD's and an extended example.

In all our definitions, we use the notation $X_\perp$ for the set $X \cup \{\perp\}$, where $\perp$ means no information.

**Definition (1.2.1.1):** A Formalized Data Flow Diagram (FDFD) is a quintuple

$$FDFD = (B, FLOWNAMES, TYPES, P, F),$$

where $B$ is a set of bubbles, $FLOWNAMES$ is a set of flows, $TYPES$ is a set of types, $P$ is the set \{persistent, consumable\} and $F = B \times FLOWNAMES \times TYPES \times B \times P$. The following notational convention for members from these domains is used: $b \in B, fn \in FLOWNAMES, T \in TYPES, p \in P, f \in F$.

**Definition (1.2.1.2):** We define the following auxiliary functions for describing the structure of an FDFD:

<table>
<thead>
<tr>
<th>Function</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Source</td>
<td>$F \rightarrow B$</td>
</tr>
<tr>
<td>FlowName</td>
<td>$F \rightarrow FLOWNAMES$</td>
</tr>
<tr>
<td>TypeOf</td>
<td>$F \rightarrow TYPES$</td>
</tr>
<tr>
<td>Target</td>
<td>$F \rightarrow B$</td>
</tr>
<tr>
<td>Consumable</td>
<td>$F \rightarrow Boolean$</td>
</tr>
<tr>
<td>Inputs</td>
<td>$B \rightarrow PowerSet(F)$</td>
</tr>
<tr>
<td>Outputs</td>
<td>$B \rightarrow PowerSet(F)$</td>
</tr>
<tr>
<td>TypeMeaning</td>
<td>$TYPES \rightarrow Set$</td>
</tr>
</tbody>
</table>

In the previous definition, we think of a type as describing a set of objects. The set of objects associated with a type $T$ is given by $TypeMeaning(T)$. By $Set$, we mean the class of all recursive sets.
**Definition (1.2.1.3):** We define the following domains describing the configuration of an FDFD:

<table>
<thead>
<tr>
<th>Notation for Members ∈ Name</th>
<th>= description</th>
</tr>
</thead>
<tbody>
<tr>
<td>( m \in \text{MODES} )</td>
<td>{idle, working}</td>
</tr>
<tr>
<td>( bm \in \text{BubbleMode} )</td>
<td>( B \to \text{MODES} )</td>
</tr>
<tr>
<td>( o \in \text{OBJECTS} )</td>
<td>( \bigcup_{T \in \text{TYPES}} \text{TypeMeaning}(T) )</td>
</tr>
<tr>
<td>( s \in \text{WhatRead} )</td>
<td>( (F \to \text{OBJECTS}_\perp) )</td>
</tr>
<tr>
<td>( r \in \text{Read} )</td>
<td>( B \to \text{WhatRead} )</td>
</tr>
<tr>
<td>( fs \in \text{FlowState} )</td>
<td>( F \to \text{OBJECTS}^* )</td>
</tr>
</tbody>
</table>

\( \gamma = (bm, r, fs) \in \) \( \text{BubbleMode} \times \text{Read} \times \text{FlowState} \)

We call \( \gamma = (bm, r, fs) \in \), a state (or a configuration) of an FDFD.

**Definition (1.2.1.4):** Sequences of objects, i.e., elements of \( \text{OBJECTS}^* \), are treated as FIFO queues using the following constants and operations:

\[
\begin{align*}
\emptyset &: \text{OBJECTS}^* \\
\text{Enq} &: (\text{OBJECTS}^*)_{\perp} \times \text{OBJECTS} \to (\text{OBJECTS}^*)_{\perp} \\
\text{IsEmpty} &: (\text{OBJECTS}^*)_{\perp} \to \text{Boolean}_{\perp} \\
\text{Head} &: (\text{OBJECTS}^*)_{\perp} \to \text{OBJECTS}_{\perp} \\
\text{Rest} &: (\text{OBJECTS}^*)_{\perp} \to (\text{OBJECTS}^*)_{\perp}
\end{align*}
\]

These operations are defined to satisfy the following equations for all \( q \in \text{OBJECTS}^* \) and \( o \in \text{OBJECTS} \).

\[
\begin{align*}
\text{Enq}(\perp, o) &= \perp \\
\text{IsEmpty}(\perp) &= \perp \\
\text{IsEmpty}(\emptyset) &= \text{true} \\
\text{IsEmpty}(\text{Enq}(q, o)) &= \text{false} \\
\text{Head}(\perp) &= \perp \\
\text{Head}(\emptyset) &= \perp \\
\text{Head}(\text{Enq}(q, o)) &= \text{if } \text{IsEmpty}(q) \text{ then } o \text{ else } \text{Head}(q) \text{ fi} \\
\text{Rest}(\perp) &= \perp \\
\text{Rest}(\emptyset) &= \perp \\
\text{Rest}(\text{Enq}(q, o)) &= \text{if } \text{IsEmpty}(q) \text{ then } \emptyset \text{ else } \text{Enq}(\text{Rest}(q), o) \text{ fi}
\end{align*}
\]
The things that the bubbles in an FDFD can do are defined through three curried functions Enabled, Consume, and Produce defined as follows:

**Definition (1.2.1.5):** Enablement of a bubble can depend on both the presence of values on input flows as well as on the values on such flows:

\[
\text{Enabled} : B \rightarrow (\text{FlowState} \rightarrow \text{Boolean})
\]

A bubble that is enabled can change its mode from *idle* to *working*. It reads some of its inflows, and consumes some of these. Only consumable flows may be consumed and consumption means removing the head of the sequence associated with the flow:

\[
\text{Consume} : B \rightarrow ((\text{FlowState} \times \text{Read}) \rightarrow \text{PowerSet}(\text{FlowState} \times \text{Read})).
\]

A bubble in *working* mode can produce some output in the transition from *working* to *idle*:

\[
\text{Produce} : B \rightarrow ((\text{FlowState} \times \text{Read}) \rightarrow \text{PowerSet}(\text{FlowState} \times \text{Read})).
\]

The notation \([x \mapsto y]g\) is an update to a function, \(g\), and it is defined by the following equation.

\[
[x \mapsto y]g \overset{\text{def}}{=} \lambda z. \text{if } z = x \text{ then } y \text{ else } g(z)
\]

The curried function \(\text{In}(f, b)\) represents the changes that \(b\) makes to the flow state and read function by reading the flow \(f\), and it is defined as follows:

\[
\text{In} : (F \times B) \rightarrow ((\text{FlowState} \times \text{Read}) \rightarrow (\text{FlowState} \times \text{Read}))
\]

\[
\text{In}(f, b)(fs, r) =
\]

\[
\text{let } r_0 = [f \mapsto \text{Head}(fs(f))](r(b))
\]

\[
\text{in } \text{if } \text{Consumable}(f) \text{ then } [f \mapsto \text{Rest}(fs(f))]|fs \text{ else } fs, b \to r_0|r
\]

By analogy, the curried function \(\text{Out}(o, f, b)\) represents the changes that \(b\) makes to the flow state and read function by producing \(o\) on the flow \(f\), and it is defined as follows:

\[
\text{Out} : (\text{OBJECTS} \times F \times B) \rightarrow ((\text{FlowState} \times \text{Read}) \rightarrow (\text{FlowState} \times \text{Read}))
\]

\[
\text{Out}(o, f, b)(fs, r) =
\]

\[
\text{let } r_0 = \lambda f'. \bot
\]

\[
\text{in } \text{if } \text{Consumable}(f) \text{ then } [f \mapsto \text{Enq}(fs(f), o)]|fs \text{ else } [f \mapsto \text{Enq}(), o]|fs, b \to r_0|r
\]
Two kinds of transitions are allowed between configurations: an enabled bubble can go from idle to working, and a working bubble can go to idle. We use the symbol \( \rightarrow \) to state the binary relation between configurations.

The transition rule

\[
\begin{align*}
& bm(b) = \text{idle}, \\
& \text{Enabled}(b)(fs) = \text{true}, \\
& bm' = [b \mapsto \text{working}]bm, \\
& (fs', r') \in \text{Consume}(b)(fs, r) \\
& (bm, r, fs) \rightarrow (bm', r', fs')
\end{align*}
\]

states that if \( b \) is \( \text{idle} \) and enabled, then it may change its mode to \( \text{working} \) and consume some of its inputs. Finally, if the conditions above the horizontal line hold, then the transition below the line may take place.

The transition rule

\[
\begin{align*}
& bm(b) = \text{working}, \\
& bm' = [b \mapsto \text{idle}]bm, \\
& (fs', r') \in \text{Produce}(b)(fs, r) \\
& (bm, r, fs) \rightarrow (bm', r', fs')
\end{align*}
\]

states that if \( b \) is \( \text{working} \), then it may change its mode to \( \text{idle} \) and produce some outputs.

We next define what we mean by a Reduced Data Flow Diagram (RDFD). We do not explicitly state that there are no stores in RDFD’s since stores are considered as an addition to, but not as a part of the FDFD’s defined in [LWBL96].

**Definition (1.2.1.6):** An FDFD that obeys to the following restrictions is called a Reduced Data Flow Diagram (RDFD):

(i) The set \( OBJECTS \), that contains all types of objects that may appear on flows, is finite.

(ii) The mappings \( \text{Enabled} \), \( \text{Consume} \), and \( \text{Produce} \) contain no higher logical constructor than First Order Predicate Calculus (FOPC) assertions over the values on the inflows and outflows of the bubble. Each assertion must be computable ([WBL93]).

(iii) The mappings \( \text{Enabled}(b) \) and \( \text{Consume}(b) \) do not make use of the positive form of the operation \( \text{IsEmpty} \). Instead, it only occurs with a negation, i.e., \( \neg\text{IsEmpty}(fs(f)) \), where \( f \in \text{Inputs}(b) \).

(iv) The mappings \( \text{Enabled}(b) \) and \( \text{Consume}(b) \) only make use of the \( \text{Head} \) element of a flow \( f \in \text{Inputs}(b) \). Constructions such as “\( \text{if Head(Rest(fs(f))) = x \text{ then } \ldots \text{ fi} \)” are not allowed.
(v) Every flow is initialized, i.e., \( \forall f \in F : f_{\text{initial}}(f) \in (\text{TypeOf}(f))^* \). Also, \( bm_{\text{initial}} = b \cdot \text{idle} \) and \( r_{\text{initial}} = b \cdot \lambda f \cdot \perp \).

The finiteness of \( \text{OBJECTS} = \bigcup_{T \in \text{TYPES}} \text{TypeMeaning}(T) \) claimed in (i) guarantees that each simple primitive type and each structured primitive type only has a fixed number of elements. E.g., we can enumerate \( \text{TypeMeaning}([\text{INTEGER}]) = \{\text{MININT}, \ldots, \text{MAXINT}\} \) and assuming that \( T \) satisfies this criterion, then

\[
\text{TypeMeaning} (\text{Sequence of } T) = \{s \mid \text{length}(s) \leq c, \forall k \leq c : s[k] \in T\}
\]

for some constant \( c \).

By (ii), we can determine the result of each expression for every possible combination of inputs for this expression. Especially, we can reformulate every expression in the mappings \( \text{Enabled, Consume, and Produce} \) as finite many if – then – fi-statements that cover possible combinations of inputs. However, these statements may be nondeterministic.

Therefore, we can rewrite the mappings \( \text{Enabled, Consume, and Produce} \) of any RDFD in the following normal form. Later, we will use this normal form to simulate RDFD's by FIFO Petri Nets. If not otherwise stated, we use this normal form for all examples throughout this paper.

**Definition (1.2.1.7):** The normal form of an RDFD (\( nf\)-RDFD) is defined as follows:

\[
B_{\text{FD FD}} = \{b_1, \ldots, b_k\}
\]

\[
\text{FLOWNAMES}_{\text{FD FD}} = \{f_1, \ldots, f_l\}
\]

A bubble \( b_i \) can be never enabled (case \( E_8 \) below), it can be always enabled (case \( E_1 \)), or it is enabled if at least one of its \( m_i \) enabling conditions of its enabling rule yields \( true \) (case \( E_3 \)). An enabling condition \( j \) will yield \( true \) if the \( n_{ij1} \) consumable inflows \( f_{ij1}^c, \ldots, f_{ijn_{ij1}}^c \) are not empty, the head elements of these inflows are the values \( a_{ij1}^c, \ldots, a_{ijn_{ij1}}^c \), and the data on the \( n_{ij2} \) persistent inflows \( f_{ij1}^p, \ldots, f_{ijn_{ij2}}^p \) are the values \( a_{ij1}^p, \ldots, a_{ijn_{ij2}}^p \). An enabling condition may access only consumable flows (then \( n_{ij2} = 0 \)), only persistent flows (then \( n_{ij1} = 0 \), or consumable and persistent flows (then \( n_{ij1} > 0 \) and \( n_{ij2} > 0 \)). Also, \( f_{ijk}^c \) and \( f_{ilm}^c \) as well as \( f_{ijk}^p \) and \( f_{ilm}^p \) may be identical for some combination of \( (j, k) \) and \( (l, m) \) pairs.

\[
\forall b_i \in B : \quad Enabled(b_i) = \lambda f s . \ \text{false} \quad (E_8)
\]

or
\[ Enabled(b_i) = \lambda f . \text{true} \]  \hspace{1cm} (E_1) \\

or

\[ Enabled(b_i) = \lambda f . \]  \hspace{1cm} (E_2) \\
\quad (-\text{IsEmpty}(f_s(f^i_{1,1})) \land \ldots \land -\text{IsEmpty}(f_s(f^i_{m_i,n_{i,m_i}}))) \\
\quad \land \text{Head}(f_s(f^i_{1,1})) = \sigma^i_{1,1} \land \ldots \land \text{Head}(f_s(f^i_{m_i,n_{i,m_i}})) = \sigma^i_{m_i,n_{i,m_i}} \\
\quad \land \text{Head}(f_s(f^p_{1,1})) = \sigma^p_{1,1} \land \ldots \land \text{Head}(f_s(f^p_{m_i,n_{i,m_i}})) = \sigma^p_{m_i,n_{i,m_i}} \\
\quad \lor \ldots \lor \\
\quad (-\text{IsEmpty}(f_s(f^p_{1,m_i})) \land \ldots \land -\text{IsEmpty}(f_s(f^p_{m_i,m_{i,m_i}}))) \\
\quad \land \text{Head}(f_s(f^p_{1,1})) = \sigma^p_{1,1} \land \ldots \land \text{Head}(f_s(f^p_{m_i,n_{i,m_i}})) = \sigma^p_{m_i,n_{i,m_i}} \\
\quad \land \text{Head}(f_s(f^p_{1,m_i})) = \sigma^p_{1,m_i} \land \ldots \land \text{Head}(f_s(f^p_{m_i,m_{i,m_i}})) = \sigma^p_{m_i,m_{i,m_i}} \\
\text{where } \forall i \in \{1, \ldots, b\} : \\
m_i \geq 1, \, n_{i11}, n_{i12}, \ldots, n_{i,m_i1}, n_{i,m_i2} \geq 0 \\
F^e = \{ f^i_{1,1}, \ldots, f^i_{m_i,n_{i,m_i}} \} \\
F^p = \{ f^p_{1,1}, \ldots, f^p_{m_i,n_{i,m_i}} \} \\
F_i = F^e \cup F^p = \text{Inputs}(b_i) \\
\forall f^e \in F^e : \text{Consumable}(f) \\
\forall f^p \in F^p : \text{~Consumable}(f) \\
O^e = \{ \sigma^e_{1,1}, \ldots, \sigma^e_{1,n_{i11}}, \ldots, \sigma^e_{m_i1,1}, \ldots, \sigma^e_{m_i,n_{i,m_i1}} \} \\
O^p = \{ \sigma^p_{1,1}, \ldots, \sigma^p_{1,n_{i12}}, \ldots, \sigma^p_{m_i1,1}, \ldots, \sigma^p_{m_i,n_{i,m_i2}} \} \\
O_i = O^e \cup O^p \\
\bigcup_{i=1,\ldots,b} F_i \subset F_{PD} \\
\bigcup_{i=1,\ldots,b} O_i \subset \text{OBJECTS} \\
\text{A bubble } b_i \text{ may consume nothing if it is never enabled or always enabled (case } C_1 \text{ below). Otherwise, if several of the } m_i \text{ enabling conditions of its enabling rule are true, } b_i \text{ nondeterministically selects one of these } \text{Consume} \text{ cases, say } j, \text{ and it consumes from the } n_{ij1} \text{ consumable inflows } f^i_{ij1}, \ldots, f^i_{ijn_{ij1}}, \text{ and the } n_{ij2} \text{ persistent inflows } f^p_{ij1}, \ldots, f^p_{ijn_{ij2}} \text{ of } b_i \text{ referred to in this } \text{Consume} \text{ case (case } C_2 \text{). This implies that the head elements of the consumable inflows are removed from their queue. The persistent inflows are not modified at all.} \\
\forall b_i \in B : \\
\text{Consume}(b_i) = \lambda (f_s, r) . \{(f_s, r)\} \hspace{1cm} (C_1) \\
\text{or}
\[
\text{Consume}(b_i) = \lambda(f_s, r) \cdot \{ (f_s, [b_i \mapsto \lambda f . \top] r) \}
\]  \hspace{1cm} (P_0)

or

\[
\text{Produce}(b_i) = \lambda(f_s, r) \cdot \{ \text{Out}(u_{i11}, h_{i11}, b_i) \ldots (\text{Out}(u_{i1k_{i1}}, h_{i1k_{i1}}, b_i)(f_s, r)) \ldots ),
\]

\[
\ldots ,
\]

\[
\text{Out}(u_{i2s1}, h_{i2s1}, b_i) \ldots (\text{Out}(u_{i2s_{k_{i2}}, h_{i2s_{k_{i2}}, b_i}(f_s, r)) \ldots )\}
\]

or

\[
\text{Produce}(b_i) = \lambda(f_s, r) \cdot \{ \text{if } r(b_i)(f_{i11}^s) = \delta_{i11}^s \ldots \wedge r(b_i)(f_{i1n_{i11}}^s) = \delta_{i1n_{i11}}^s \\
\wedge r(b_i)(f_{i12}^s) = \delta_{i11}^s \ldots \wedge r(b_i)(f_{i1n_{i12}}^s) = \delta_{i1n_{i12}}^s
\}
\]  \hspace{1cm} (P_2)

A bubble \(b_i\) may produce nothing and simply reset its internal status independently from what it has read (case \(P_0\) below). It may nondeterministically select one of its \(s_i\) \textit{Produce} cases, say \(j\), producing objects \(u_{ij1}, \ldots, u_{ijk_{ij}}\) on its outsouts \(h_{ij1}, \ldots, h_{ijk_{ij}}\) (case \(P_1\)). Otherwise, if it has read some input that matches one of the \(m_i\) \textit{Consume} cases, say \(j\), it nondeterministically selects one of the \(l_{ij}\) \textit{Produce} subcases, say \(k\), and produces objects \(u_{ijk_{ij}}, \ldots, u_{ijk_{ijs_{ij}}k_{ij}}\) on its outsouts \(h_{ijk_{ij}}, \ldots, h_{ijk_{ijs_{ij}}k_{ij}}\) (case \(P_2\)). We use the symbol \(\square\) to indicate that any of the \(l_{ij}\) \textit{Produce} subcases can be selected nondeterministically if \textit{Produce} case \(j\) has been selected (nondeterministically).
then \( Out(u_{111}, h_{1111}, b_i)(\ldots (Out(u_{111q_{i1}}, h_{111q_{i1}}, b_i)(fs, r) \ldots) \)

\[
\begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
\end{array}
\]

\[
\begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
\end{array}
\]

if \( r(b_i)(f^i_{im_1}) = \sigma^i_{m_1} \land \ldots \land r(b_i)(f^i_{im_{m_1-1}}) = \sigma^i_{m_{m_1-1}} \land r(b_i)(f^i_{im_{m_1}}) = \sigma^i_{m_{m_1}} \land \ldots \land r(b_i)(f^i_{im_{m_2}}) = \sigma^i_{m_{m_2}} \)

then \( Out(u_{im_111}, h_{im_111}, b_i)(\ldots (Out(u_{im_11q_{im_1}}, h_{im_11q_{im_1}}, b_i)(fs, r) \ldots) \)

\[
\begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
\end{array}
\]

\[
\begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
\end{array}
\]

\[
\begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
\end{array}
\]

\[
\begin{array}{c}
\vdots \\
\vdots \\
\vdots \\
\end{array}
\]

where \( \forall i \in \{1, \ldots, b\} : \)

\[
\begin{array}{c}
m_i \geq 1, l_{1i}, \ldots, l_{mi}, q_{1im}, \ldots, q_{immi} \geq 0 \\
H_i = \{ h_{1i11}, \ldots, h_{1i1q_{i1}}, \ldots, h_{imi1}, \ldots, h_{imiq_{imi}} \} \\
U_i = \{ u_{1i11}, \ldots, u_{1i1q_{i1}}, \ldots, u_{imi1}, \ldots, u_{imiq_{imi}} \} \\
\bigcup_{i=1, \ldots, b} H_i \subset F_{FD FD} \\
\bigcup_{i=1, \ldots, b} U_i \subset OBJECTS
\end{array}
\]

We assume \( Consume(b_i) \) and \( Produce(b_i) \) are finite enumerable and ordered sets for every \( b_i \in B \).

Thus, we can access the \( j \)th element of \( Consume(b_i) \) through \( (Consume(b_i))_j \) and the \( k \)th element of \( Produce(b_i) \) through \( (Produce(b_i))_k \).

**Definition (1.2.1.8):** An RDFD that does not have any persistent flows is called a persistent flow-free Reduced Data Flow Diagram (PFF-RDFD). This implies that \( F = B \times FLOWNAMES \times TYPES \times B \times \{\text{consumable}\} \).
**Definition (1.2.1.9):** A firing sequence (computation sequence) of an FDFD is a possibly infinite sequence \((b_i, a_i, j_i) \in B \times \{C, P\} \times \mathbb{N}, i \geq 0\), such that, if transition \((b_i, a_i, j_i)\) is fired in state \((bm, r, fs)\), then
\[
(fs', r') = \begin{cases} 
(\text{Consume}(b_i))_j, (fs, r), & \text{if } a_i = C \\
(\text{Produce}(b_i))_j (fs, r), & \text{if } a_i = P
\end{cases}
\]
and
\[
bm'(b_i) = \begin{cases} 
\text{working}, & \text{if } a_i = C \\
\text{idle}, & \text{if } a_i = P
\end{cases}
\]
By induction, we extend this notation for firing sequences:
\[
(bm, r, fs)[(b_1, a_1, j_1), \ldots, (b_{n-1}, a_{n-1}, j_{n-1}), (b_n, a_n, j_n)]
\]
is used to indicate that transition \((b_n, a_n, j_n)\) is fireable in state \((bm_{n-1}, r_{n-1}, fs_{n-1})\), given that
\[
(bm, r, fs)[(b_1, a_1, j_1), \ldots, (b_{n-1}, a_{n-1}, j_{n-1})](bm_{n-1}, r_{n-1}, fs_{n-1})
\]
holds. By analogy, we use
\[
(bm, r, fs)[(b_1, a_1, j_1), \ldots, (b_{n}, a_{n}, j_{n})](bm_n, r_n, fs_n)
\]
to indicate that state \((bm_n, r_n, fs_n)\) is reached upon the firing of the sequence \((b_1, a_1, j_1), \ldots, (b_n, a_n, j_n)\).

**Definition (1.2.1.10):** The set of firing sequences (set of computation sequences, language) of an FDFD, denoted by \(FS(FDFD, \gamma_{\text{initial}})\), is the set containing all firing sequences that are possible for this FDFD, given \(\gamma_{\text{initial}} = (bm_{\text{initial}}, r_{\text{initial}}, fs_{\text{initial}}) = (bm_0, r_0, fs_0)\), i.e.,
\[
FS(FDFD, \gamma_{\text{initial}}) = \{s \mid s \in (B \times \{C, P\} \times \mathbb{N})^* \land \gamma_{\text{initial}}[s]\}.
\]

**Definition (1.2.1.11):** The Reachability Set of an FDFD, denoted by \(RS(FDFD, \gamma_{\text{initial}})\), is the set of states \(\gamma = (bm, r, fs)\) that are reachable from \(\gamma_{\text{initial}} = (bm_{\text{initial}}, r_{\text{initial}}, fs_{\text{initial}})\), i.e.,
\[
RS(FDFD, \gamma_{\text{initial}}) = \{\gamma \mid \exists s \in FS(FDFD, \gamma_{\text{initial}}) : \gamma_{\text{initial}}[s] \gamma\}.
\]
1.2.2 FIFO Petri Nets

In some sense, FIFO Petri Nets (introduced in [MM81]) are Petri Nets where places contain words instead of tokens and arcs are labelled by words. More formally, we make use of the definition of FIFO Petri Nets as given in [Rou87].

**Definition (1.2.2.1):** A FIFO Petri Net is a quintuple $FPN = (P, T, B, F, Q)$ where $P$ is a finite set of places (also called queues), $T$ is a finite set of transitions (disjoint from $P$), $Q$ is a finite queue alphabet, and $F : T \times P \rightarrow Q^*$ and $B : P \times T \rightarrow Q^*$ are two mappings called respectively forward and backward incidence mappings.

**Definition (1.2.2.2):** A marking $M$ of a FIFO Petri Net is a mapping $M : P \rightarrow Q^*$.

A transition $t$ is fireable in $M$, written $M(t >)$, if $\forall p \in P : B(p, t) \leq M(p)$ (where $u \leq x$ means $u$ is a prefix of $x$).

For a marking $M$, we define the firing of a transition $t$, written $M(t > M')$, if $M(t >$ and the following equation between words holds $\forall p \in P : B(p, t)M'(p) = M(p)F(t, p)$. That means, the firing of a transition $t$ removes $B(p, t)$ from the head of $M(p)$ and appends $F(t, p)$ to the end of the resulting word.

**Definition (1.2.2.3):** A FIFO Petri Net $FPN$ together with an initial marking $M_0 : P \rightarrow Q^*$ is called a marked FIFO Petri Net and is denoted by $(FPN, M_0)$.

As usual, the firing of a transition can be extended to the firing of a sequence of transitions. We denote by $FS(FPN, M_0)$ the set of firing sequences of this FIFO Petri Net. The firing of a sequence $u$ of transitions from a marking $M$ to a marking $M'$ is written as $M(u > M')$.

The set of markings that are reachable from $M_0$ is called Reachability Set and it is denoted by $Acc(FPN, M_0)$.

1.2.3 Program Machines

We introduce Program Machines as given in [Min67], using the formalism of [VVN81].

**Definition (1.2.3.1):** A Program Machine is given by a finite set $R = \{r_1, \ldots, r_p\}$ of registers, a finite set $Q = \{q_1, \ldots, q_r\}$ of labels, and a finite set $I$ of instructions. Each instruction is labelled by an element of $Q$ and no two instructions have the same label. A Program Machine has exactly one “start
instruction”

\[ q_0 \text{ : start goto } q_1; \]

and exactly one “halt instruction”

\[ q_f \text{ : halt.} \]

The other instructions are of the type “increment register \( r_i \)”

\[ q_s : r_i := r_i + 1 \text{ goto } q_m; \]

or “test and decrement register \( r_i \)”

\[ q_s : \text{if } r_i = 0 \text{ then goto } q_i \text{ else } r_i := r_i - 1 \text{ goto } q_m. \]

The registers have nonnegative integers as values. First the start instruction is executed. Then the flow of control is determined by the goto contained in each instruction, until the halt instruction is reached.

\[ \square \]

**Definition (1.2.3.2):** A computation sequence of a Program Machine is a possibly infinite sequence

\[ q_0, (k^1_1, \ldots, k^p_1, q_1), (k^1_2, \ldots, k^p_2, q_2), \ldots, (k^1_i, \ldots, k^p_i, q_i), \ldots, (k^1_r, \ldots, k^p_r, q_r) \]

with \( q_{i_j} = q_f \), i.e., the halt statement is reached. \( q_{i_j} \) is the actual instruction to be executed in step \( j \) and \( k^i_j \) is the content of register \( r_i \) just before the execution of instruction \( q_{i_j} \) in step \( j \). In computations, arbitrary initial values \((k^1_1, \ldots, k^p_1) \in \mathbb{N}^p \) are allowed. Note that computations may be of infinite length.

\[ \square \]

### 1.2.4 Computation Systems and Homomorphisms

Now we will introduce the overall concept of a Computation System. All the definitions and results in this subsection are drawn from [KM82]. However, there exist similar approaches in the literature, e.g., in [Jen80], where the terms “transition system”, “simulation”, and “consistent homomorphism” have been defined with respect to a formal method that allows comparisons of the descriptive power of different types of Petri Nets.

For any set \( \Sigma \), we denote by \( \Sigma^* \) the set of finite sequences of elements of \( \Sigma \) including the null sequence \( \lambda \). The set of infinite sequences of elements of \( \Sigma \) is denoted by \( \Sigma^\omega \) and we define \( \Sigma^\omega = \Sigma^\infty \cup \Sigma^* \).

**Definition (1.2.4.1):** A computation system \( S = (\Sigma, D, x, \rightarrow) \) consists of a set \( D \), an element \( x \) of \( D \), a finite set \( \Sigma \) of operations, and a function \( \rightarrow \) from \( \Sigma \) to the set of partial functions from \( D \) to
D. That is, for each $a \in \Sigma$, $\pi$ is a partial function from $D$ to $D$. The function $\bar{\pi}$ is extended to $\Sigma^*$ by $\bar{\pi} = \text{identity}$, $\bar{\alpha \beta}(y) = \bar{\pi} \cdot \overline{\mathcal{A}}(y) = \overline{\mathcal{A}(\pi(y))}$, $\alpha, \beta \in \Sigma^*$, $y \in D$.

Here $D$ is intuitively thought of as the set of states (or configurations) of the computation system, where a state includes control information as well as data for synchronization. The element $x$ is then considered to be the initial state of the system. The performance of an operation will create a new state, as defined by the function $\bar{\pi}$, and a sequence of operation performances can be thought of as a computation (or firing) sequence of the system.

**Definition (1.2.4.2):** Let $S = (\Sigma, D, x, \overline{\cdot})$ be a computation system. Let $y, z \in D$, and $\alpha \in \Sigma^*$. We define:

\[
\begin{align*}
\overline{\pi}(y) &= \top, & &\text{if } \overline{\pi}(y) \text{ is undefined} \\
\overline{\pi}(y) &= \bot, & &\text{if } \overline{\pi}(y) \text{ is defined} \\
y \overrightarrow{\alpha} z, & &\text{if } \overline{\pi}(y) = z \\
y \overrightarrow{\ast} z, & &\text{if } \exists \alpha \in \Sigma^* : y \overrightarrow{\alpha} z
\end{align*}
\]

**Definition (1.2.4.3):** Let $S = (\Sigma, D, x, \overline{\cdot})$ be a computation system. For each $y \in D$, a **computation sequence** from $y$ is a (finite or infinite) sequence $a_1a_2\ldots$ of elements of $\Sigma$ such that $\forall i : \overline{a_1a_2\ldots a_i}(y) \neq \bot$. We denote by $C_S^y(y)$ the set of all computation sequences from $y$ and by $C_S(y) = \{ \alpha \mid \alpha \in \Sigma^*, \overline{\pi}(y) \neq \bot \}$ the set of all finite computation sequences from $y$. For each $y \in D$, we denote by $R_S(y) = \{ \overline{\pi}(y) \mid \alpha \in \Sigma^*, \overline{\pi}(y) \neq \bot \}$ the reachability set from $y$. When $y = x$, we simply write $R_S$, $C_S$, and $C_S^x$ instead of $R_S(x)$, $C_S(x)$, and $C_S^x(x)$, respectively.

Note that for an $\alpha \in \Sigma^*$, $\alpha$ is in $C_S^y(y)$ if, and only if, every prefix of $\alpha$ is in $C_S(y)$.

The following definitions give some ideas about possible relations between different computation systems.

**Definition (1.2.4.4):** Let $S_1 = (\Sigma_1, D_1, x_1, \overline{\cdot})$ and $S_2 = (\Sigma_2, D_2, x_2, \overline{\cdot})$ be computation systems. A **homomorphism** $h = (\tau, \rho) : S_1 \to S_2$ consists of a homomorphism $\tau : \Sigma_1 \to \Sigma_2$, and an injection $\rho : D_1 \to D_2$ which satisfies the following conditions:

\[
\begin{align*}
\rho(x_1) &= x_2 \\
\forall y, z \in R_{S_1}, \forall \alpha \in \Sigma_1^* : (y \overrightarrow{\alpha} z \Rightarrow \rho(y) \overrightarrow{\tau(\alpha)} \rho(z))
\end{align*}
\]
• A homomorphism is said to be injective if \( \tau : \Sigma_1 \to \Sigma_2 \) is injective.

• A homomorphism is said to be surjective if the following conditions hold:

\[
\forall y, z \in R_S, \forall \beta \in \Sigma_2^* : (\rho(y) \xrightarrow{\beta} \rho(z) \Rightarrow \exists \alpha \in \Sigma_1^* : (\beta = \tau(\alpha) \wedge y \xrightarrow{\alpha} z)) \quad (1.2.4.4.3)
\]

\[
\forall y \in R_S, \forall \gamma' \in D_2 : (\rho(y) \xrightarrow{\gamma'} \Rightarrow \exists z \in R_S : \gamma' \xrightarrow{s} \rho(z)) \quad (1.2.4.4.4)
\]

• A homomorphism is said to be bijective if it is surjective and injective.

The injection \( \rho \) relates elements of \( D_1 \) to elements of \( D_2 \), where condition (1.2.4.4.1) states that the starting state of \( S_1 \) maps into the starting state of \( S_2 \). By condition (1.2.4.4.2), if \( \alpha \) is any computation sequence in \( S_1 \) then there is a related computation sequence \( \tau(\alpha) \) in \( S_2 \), with appropriate state mappings using \( \rho \). Condition (1.2.4.4.3) means that any computation from \( \rho(y) \) to \( \rho(z) \) in \( S_2 \) is the image of a computation from \( y \) to \( z \) in \( S_1 \). Condition (1.2.4.4.4) means that any computation from \( \rho(y) \) in \( S_2 \) is an initial segment of the image of some computation from \( y \) in \( S_1 \).

**Definition (1.2.4.5):** Let \( S = (\Sigma, D, x, \tau) \) be a computation system. Let \( \alpha, \beta \in \Sigma^* \). We write \( \alpha \simeq \beta \) if \( \alpha \) is a permutation of \( \beta \). Let \( h = (\tau, \rho) : S_1 \to S_2 \) be a homomorphism. \( h \) is said to be spanning if the following conditions hold:

\[
\forall y, z \in R_S, \forall \beta \in \Sigma_2^* : (\rho(y) \xrightarrow{\beta} \rho(z) \Rightarrow \exists \alpha \in \Sigma_1^* : \beta \simeq \tau(\alpha) \wedge y \xrightarrow{\alpha} z) \quad (1.2.4.5.1)
\]

\[
\exists k \in \mathbb{N} \forall y \in R_S, \forall y' \in D_2, \forall \beta \in \Sigma_2^* : (\rho(y) \xrightarrow{\beta} y' \Rightarrow \exists \alpha \in \Sigma_1^* \exists z \in D_1 \exists j' \in D_2 \exists \beta', \beta'' \in \Sigma_2^* : \rho(y) \xrightarrow{\tau(\alpha)} \rho(z) \xrightarrow{\beta'} j' \wedge y' \xrightarrow{\beta'} j' \wedge \tau(\alpha) \beta'' \simeq \beta \beta' \wedge |\beta''| \leq k) \quad (1.2.4.5.2)
\]

\[
(z \xrightarrow{\gamma} u \text{ in } S_1) \Rightarrow \exists u' \in D_2 \exists \gamma', \gamma'' \in \Sigma_2^* : j' \xrightarrow{\gamma'} u' \wedge \rho(u) \xrightarrow{\gamma''} u' \wedge \tau(\gamma) \gamma'' \simeq \beta \beta' \gamma' \quad (1.2.4.5.3)
\]

Condition (1.2.4.5.2) means that any computation \( \beta \) from \( \rho(y) \) of \( S_2 \) is a prefix of a permutation of a computation of the form \( \tau(\alpha) \beta'' \), \( \alpha \in \Sigma_1^* \), \( |\beta''| \leq k \). If \( \alpha \gamma \) is a computation from \( y \) of \( S_1 \), then there must be a computation of the form \( \beta \beta' \gamma' \) such that \( \tau(\alpha) \gamma \) is a prefix of a permutation of \( \beta \beta' \gamma' \). Intuitively, \( \beta \) is an initial segment of a simulation of \( \tau(\alpha) \), and if \( \alpha \gamma \) is a computation of \( S_1 \), then \( \beta \) can be followed by a computation to simulate \( \tau(\gamma) \).

**Theorem (1.2.4.6):** Every surjective homomorphism is a spanning homomorphism.
Definition (1.2.4.7): Let \( h = (\tau, \rho) : S_1 \to S_2 \) be a homomorphism. \( h \) is said to be length preserving if \( \forall a \in \Sigma_1 : |\tau(a)| = 1. \)

Definition (1.2.4.8): Let \( \Sigma \) be a finite set. For each \( w \in \Sigma^* \), let \( \iota(w) \) be the subset of \( \Sigma \) defined by \( \iota(w) = \{ a \mid a \alpha \beta = w, \alpha, \beta \in \Sigma^*, a \in \Sigma \}. \)

Let \( h = (\tau, \rho) : S_1 \to S_2 \) be a surjective homomorphism. \( h \) is said to be principal if for each \( a \) and \( b \) in \( \Sigma_1 \), either \( \tau(a) = \tau(b) \) or \( \iota(\tau(a)) \cap \iota(\tau(b)) = 0 \), and \( \pi \neq \emptyset \) implies \( \iota(\tau(a)) \cap \iota(\tau(b)) = 0 \).

Theorem (1.2.4.9): Let \( h = (\tau, \rho) : S_1 \to S_2 \) be a bijective homomorphism. For each \( y, z \in R_\Sigma \) and \( a \in \Sigma_1^* \) it holds that
\[
y \xrightarrow{\alpha} z \text{ if, and only if, } \rho(y) \xrightarrow{\tau(a)} \rho(z).
\]

Definition (1.2.4.10): Let \( h = (\tau, \rho) : S_1 \to S_2 \) be a homomorphism. \( h \) is called an isomorphism if there is a homomorphism \( h' = (\tau', \rho') : S_2 \to S_1 \) such that \( hh' : S_2 \to S_2 \) and \( h'h : S_1 \to S_1 \) are identities, i.e., \( \tau' \rho' : \Sigma_2^* \to \Sigma_2^* \), \( \tau' : \Sigma_1^* \to \Sigma_1^* \), \( \rho' : D_2 \to D_2 \), and \( \rho : D_1 \to D_1 \) are identities.

Theorem (1.2.4.11): Let \( S_1 = (\Sigma_1, D_1, x_1, \boxed{}^\alpha) \) and \( S_1 = (\Sigma_2, D_2, x_2, \boxed{}^\beta) \) be computation systems. Let \( \tau : \Sigma_1^* \to \Sigma_2^* \) be a homomorphism and \( \rho : D_1 \to D_2 \) be a function. Then \( h = (\tau, \rho) \) is an isomorphism from \( S_1 \) to \( S_2 \) if, and only if, \( \tau \) and \( \rho \) are bijective and satisfy conditions (1.2.4.4.1) and (1.2.4.9.1).

Definition (1.2.4.12): A computation system \( S = (\Sigma, D, x, \boxed{}^\gamma) \) is said to be reduced if \( D = R_\Sigma \). For each computation system \( S = (\Sigma, D, x, \boxed{}^\gamma) \), the computation system \( \hat{S} = (\Sigma, R_\Sigma, x, \boxed{}^\gamma) \) is called the reduced form of \( S \), where for each \( a \in \Sigma \), the partial function \( \pi \) in \( \hat{S} \) is the restriction \( \pi \mid R_\Sigma \) of \( \pi \in S \).

Theorem (1.2.4.13): Let \( S_1 \) and \( S_2 \) be reduced computation systems. Let \( h = (\tau, \rho) : S_1 \to S_2 \) be a homomorphism. \( h \) is an isomorphism if, and only if, \( h \) is length preserving and bijective.

1.3 Equivalence of PFF–RDFD’s and Turing Machines

In this section, we will show that PFF–RDFD’s and Turing Machines are equivalent with respect to their computational power. Since we know that Turing Machines, Program Machines, and FIFO Petri
Nets are equivalent ([Min67], [FM82], and [MF85], respectively), it is sufficient to show that we can simulate each RDFD, and hence each PFF-RDFD, by a FIFO Petri Net and each Program Machine by a PFF-RDFD. Actually, the first simulation could be omitted and instead, we could simply invoke Church’s Thesis to deduce that PFF-RDFD’s have at most the computational power of Turing Machines (and thus of FIFO Petri Nets). However, we will show a little bit more than only the existence of a simulation, but also that the simulation of RDFD’s (and thus of PFF-RDFD’s) by FIFO Petri Nets is based on an isomorphism. For the other direction, a PFF-RDFD is sufficient to simulate a Program Machine.

Now, we will formally state our main result of this paper. The proof follows by the above and Theorems (1.3.1.1) and (1.3.2.1).

**Theorem (1.3.1):** PFF-RDFD’s and Turing Machines have the same computational power.

1.3.1 Simulation of RDFD’s by FIFO Petri Nets

**Theorem (1.3.1.1):** Every RDFD can be simulated by a FIFO Petri Net with respect to an isomorphism $h$.

**Proof:** Without loss of generality, we assume that our RDFD is given as a nf-RDFD $(B_{RDFD}, FLOWNAMES_{RDFD}, TYPES_{RDFD}, P_{RDFD}, F_{RDFD})$ with mappings $Enabled$, $Consume$, and $Produce$ and with initial values $(bm_{initial}, r_{initial}, f_{s initial})$. We consider the computation system

$$S_{RDFD} = ((B_{RDFD}, \{C, P\}, N), (bm, r, f), (bm_{initial}, r_{initial}, f_{s initial}), \mathbb{RDFD})$$

We now construct a marked FIFO Petri Net $FPN = (\langle P_{FPN}, T_{FPN}, B_{FPN}, F_{FPN}, Q_{FPN} \rangle, M_{\emptyset, FPN})$ as follows:

For each flow in the RDFD we generate a place in the FIFO Petri Net. For an easier reference we assume that $\forall i = 1, \ldots, f \in FLOWNAMES_{RDFD} : FlowName(f_i) = f_i$. For each bubble in the RDFD we require additional places in the FIFO Petri Net to store the bubble’s working mode and the values that have been read. Whenever we refer to type $C_1, C_2, P_0, P_1$, and $P_2$, we mean that the $Consume$ or $Produce$ case is in the related normal form, introduced in Definition (1.2.1.7).

$$P_{FPN} = \{f_1, \ldots, f_f\} \cup \{b_{i, idle}, \ldots, b_{b, idle}\} \cup \bigcup_{i \in \{1, \ldots, b\}} \{b_{i, working}, 1 \mid Consume(b_i) \text{ is of type } C_1\}$$
For each case (subcase) in the mappings \textit{Consume} and \textit{Produce}, we generate a transition in the FIFO Petri Net.

\[
T_{FPN} = \bigcup_{i \in \{1, \ldots, \beta\}} \left( \left\{ c_{i1} \mid \text{Consume}(b_i) \text{ is of type } C_1 \right\} \cup \left\{ e_{i1}, \ldots, e_{im_i} \mid \text{Consume}(b_i) \text{ is of type } C_2, m_i = \text{(# of cases in } \text{Consume}(b_i)) \right\} \cup \left\{ p_{i1}, \ldots, p_{is_i} \mid \text{Produce}(b_i) \text{ is of type } P_1, s_i = \text{(# of cases in } \text{Produce}(b_i)) \right\} \cup \left\{ p_{i11}, \ldots, p_{iim_i1}, \ldots, p_{im_i1}, \ldots, p_{im_i1m_i} \mid \text{Produce}(b_i) \text{ is of type } P_1, m_i = \text{(# of cases in } \text{Produce}(b_i)), t_{ij} = \text{(# of subcases in case } j \text{ in } \text{Produce}(b_i)) \right\} \right)
\]

For each \( b_i \in B_{RDPD} \), define the mappings \( B_{FPN} \) and \( F_{FPN} \) in accordance with the mappings \textit{Consume} and \textit{Produce}.

If \( \text{Consume}(b_i) \) is of type \( C_1 \), then upon firing of transition \( c_{i1} \) the idle token \( I \) is removed from place \( b_{i, \text{idle}} \) and the working token \( W \) is queued at place \( b_{i, \text{working}} \). We define:

\[
B(b_{i, \text{idle}}, c_{i1}) = I
\]

\[
F(c_{i1}, b_{i, \text{working}}) = W
\]

If \( \text{Consume}(b_i) \) is of type \( C_2 \), then upon firing of transition \( c_{ij} \) the idle token \( I \) is removed from place \( b_{i, \text{idle}} \), the tokens \( o_{ij1}, \ldots, o_{ijn_{ij1}} \) are removed from the places \( f_{ij1}, \ldots, f_{ijn_{ij1}} \) representing consumable flows, the tokens \( o_{ij1}, \ldots, o_{ijn_{ij2}} \) are removed from the places \( f_{ij1}, \ldots, f_{ijn_{ij2}} \) representing persistent flows, the working token \( W \) is queued at place \( b_{i, \text{working}} \) and the tokens \( o_{ij1}, \ldots, o_{ijn_{ij2}} \) are queued at places \( f_{ij1}, \ldots, f_{ijn_{ij2}} \) representing persistent flows. We define:

\[
B(b_{i, \text{idle}}, c_{i1}) = I
\]

\[
B(b_{i, \text{idle}}, c_{im_i}) = I
\]

\[
B(f_{i11}, c_{i1}) = o_{i11}
\]

\[
B(f_{i1n_{i1}}, c_{i1}) = o_{i1n_{i1}}
\]
\[ \begin{align*}
B(f_{111}^p, c_{i1}) &= o_{i11}^p \\
& \quad \vdots \\
B(f_{1n2}^p, c_{i1}) &= o_{i1n2}^p \\
& \quad \vdots \\
B(f_{im1}^p, c_{im}) &= o_{im1}^p \\
& \quad \vdots \\
B(f_{im1}^p, c_{im}) &= o_{imn1}^p \\
B(f_{im1}^p, c_{im}) &= o_{im1}^p \\
& \quad \vdots \\
B(f_{im2}^p, c_{im}) &= o_{imn2}^p
\end{align*} \]

\[ \begin{align*}
F(c_{i1}, b_{i, \text{working}1}) &= W \\
& \quad \vdots \\
F(c_{im}, b_{i, \text{working}m}) &= W
\end{align*} \]

\[ \begin{align*}
F(c_{i1}, f_{111}^p) &= o_{i11}^p \\
& \quad \vdots \\
F(c_{i1}, f_{1n2}^p) &= o_{i1n2}^p \\
& \quad \vdots \\
F(c_{im}, f_{im1}^p) &= o_{im1}^p \\
& \quad \vdots \\
F(c_{im}, f_{imn2}^p) &= o_{imn1}^p
\end{align*} \]

If \( \text{Produce}(b_i) \) is of type \( P_1 \), then upon firing of transition \( p_{ij} \) the working token \( W \) is removed from place \( b_{i, \text{working}ij} \), the idle token \( I \) is queued at place \( b_{i,i\cdot\text{idle}} \), and the tokens \( u_{ij1}, \ldots, u_{ijk_{ij}} \) are queued at places \( h_{ij1}, \ldots, h_{ijk_{ij}} \). We define:

\[ \begin{align*}
B(b_{i, \text{working}1}, p_{i1}) &= W \\
& \quad \vdots \\
B(b_{i, \text{working}1}, p_{i2}) &= W
\end{align*} \]
\[
F(p_{i1}, b_{i, idle}) = I \\
\vdots \\
F(p_{is}, b_{i, idle}) = I \\
F(p_{i1}, h_{i1}) = u_{i1} \\
\vdots \\
F(p_{i1}, h_{i1k}) = u_{i1k} \\
\vdots \\
F(p_{is}, h_{is1}) = u_{is1} \\
\vdots \\
F(p_{is}, h_{is,k+1}) = u_{is,k+1} \\
\]

If \textit{Produce}(b_i) is of type \(P_2\), then upon firing of transition \(p_{ijk}\) the working token \(W\) is removed from place \(b_{i, working}j\), the idle token \(I\) is queued at place \(b_{i, idle}\), and the tokens \(u_{ijk1}, \ldots, u_{ijkq, kj}\) are queued at places \(h_{ijk1}, \ldots, h_{ijkq, kj}\). Also, if place \(h_{ijk}\) represents a persistent flow, any value that is currently queued at this place will be removed upon firing of this transition. We define:

\[
B(b_{i, working1}, p_{i1}) = W \\
\vdots \\
B(b_{i, working1}, p_{i1k}) = W \\
\vdots \\
B(b_{i, workingm}, p_{im}) = W \\
\vdots \\
B(b_{i, workingm}, p_{im,k}) = W \\
\]

\[
F(p_{i1}, b_{i, idle}) = I \\
\vdots \\
F(p_{i1k}, b_{i, idle}) = I \\
\vdots \\
F(p_{im}, b_{i, idle}) = I \\
\]
\[ F(p_{im,i_{im_i}}, b_{i,i_{dte}}) = I \]

\[ F(p_{1i1}, h_{i11}) = u_{i11} \]

\[ \vdots \]

\[ F(p_{i11}, h_{i11q_{i11}}) = u_{i11q_{i11}} \]

\[ \vdots \]

\[ F(p_{i11}, h_{i11}) = u_{i11} \]

\[ \vdots \]

\[ F(p_{i11}, h_{i11q_{i11}}) = u_{i11q_{i11}} \]

\[ \vdots \]

\[ F(p_{im_1}, h_{im_1}) = u_{im_1} \]

\[ \vdots \]

\[ F(p_{im_1}, h_{im_1q_{im_1}}) = u_{im_1q_{im_1}} \]

\[ \vdots \]

\[ F(p_{im_1}, h_{im_1q_{im_1}}) = u_{im_1q_{im_1}} \]

\[ \vdots \]

\[ F(p_{im_1}, h_{im_1q_{im_1}}) = u_{im_1q_{im_1}} \]

\[ B(h_{i111}, p_{i11}) = \text{any, if } \neg \text{Consumable}(h_{i111}) \]

\[ \vdots \]

\[ B(h_{i11q_{i11}}, p_{i11}) = \text{any, if } \neg \text{Consumable}(h_{i11q_{i11}}) \]

\[ \vdots \]

\[ B(h_{im_1}, p_{im_1}) = \text{any, if } \neg \text{Consumable}(h_{im_1}) \]

\[ \vdots \]

\[ B(h_{im_1q_{im_1}}, p_{im_1}) = \text{any, if } \neg \text{Consumable}(h_{im_1q_{im_1}}) \]

If nothing is produced for a particular combination of reads (case \( P_0 \)), only the equations that involve \( b_{i, \text{working}} \) and \( b_{i,i_{dte}} \) are defined in that case.
The queue alphabet of the FIFO Petri Net is defined as follows:

\[ Q_{FPN} = OBJECTS_{RDFD} \cup \{ I, W \} \]

The initial marking \( M_0_{FPN} \) is such that:

\[
M_{0, FPN}(b_{i, idle}) = I \quad \forall i \in \{1, \ldots, b\}
\]

\[
M_{0, FPN}(b_{i, working}) = W \quad \forall i \in \{1, \ldots, b\} \forall j \in \{1, \ldots, m_i\}
\]

\[
M_{0, FPN}(f_j) = fs(f_j) \quad \forall j \in \{1, \ldots, f\}, f_j \in RDFD
\]

Then, the computation system \( S_{FPN} = (T_{FPN}, M_{FPN}, M_{0, FPN}, FPN) \) is realized by the FIFO Petri Net \( FPN \). Consider the homomorphism \( h = (\tau, \rho) : S_{RDFD} \rightarrow S_{FPN} \) where the homomorphism \( \tau : (B_{RDFD}, \{C, P\}, N)^* \rightarrow T^*_{FPN} \) and the injection \( \rho : (bm, r, fs) \rightarrow M_{FPN} \) are defined as follows:

\[
\tau((b_i, a, n)) =
\begin{cases}
  c_{in}, & \text{if } a = C \\
  p_{in}, & \text{if } a = P \text{ and } \text{Produce}(b_i) \text{ is of type } P_1 \\
  p_{in_{out}}, & \text{if } a = P, \text{Produce}(b_i) \text{ is of type } P_2, \text{ and } n = \sum_{j=1}^{n-1} b_{ij} + n_1
\end{cases}
\]

\( \rho(bm, r, fs) \) is such that \( \forall i \in \{1, \ldots, b\} \forall j \in \{1, \ldots, m_i\} \)

\[
M_{FPN}(b_{i, idle}) =
\begin{cases}
  I, & \text{if } bm(b_i) = \text{idle} \\
  <>, & \text{if } bm(b_i) = \text{working}
\end{cases}
\]

\[
M_{FPN}(b_{i, working}) =
\begin{cases}
  W, & \text{if } bm(b_i) = \text{working}, (\text{Consume}(b_i))_j \text{ has been executed} \\
  <>, & \text{if } bm(b_i) = \text{working}, \exists k, k \neq j : (\text{Consume}(b_i))_k \text{ has been executed}
\end{cases}
\]

and \( \forall j \in \{1, \ldots, f\}, f_j \in RDFD \)

\[
M_{FPN}(f_j) = fs(f_j).
\]

Obviously, \( \tau \) and \( \rho \) are bijective. Also, \( h \) satisfies (1.2.4.1) and (1.2.4.9.1). Hence, \( h \) is an isomorphism by Theorem (1.2.4.11).

According to the Definitions and Theorems from [KM82], here summarized in Subsection 1.2.4, the isomorphism \( h \) constructed in the previous proof is also a bijective (hence injective, surjective, hence spanning), length preserving, and principal homomorphism.

**Example (1.3.1.2):** We will provide a small example how to construct a FIFO Petri Net for a given \( n^f\)-RDFD. Our \( n^f\)-RDFD only consists of three bubbles \( A, B, \) and \( C \), two consumable flows \( f \) and \( out \), and two persistent flows \( g \) and \( h \) (see Figure 1.1). Bubble \( A \) only produces combinations of \( X \)}}
on flow $f$ and 0 on flow $g$ or $Y$ on flow $f$ and 1 on flow $g$. Bubble $B$ can forward any value on flow $h$ if it reads a 1 on flow $g$. It must forward the same value if it reads a 0 on flow $g$. Therefore, bubble $C$ can read all possible combinations $X/0$, $X/1$, $Y/0$, and $Y/1$ on its flows $f$ and $h$. Initially, flows $g$ and $h$ both contain a 0. All other flows are empty.

![Diagram](image)

Figure 1.1: nf-RFD.

The mappings $Enabled$, $Consume$, and $Produce$ for the nf-RFD shown in Figure 1.1 are specified as follows:

$$Enabled(A) = \lambda fs . true$$

$$Enabled(B) = \lambda fs . \text{Head}(fs(g)) = 0 \lor \text{Head}(fs(g)) = 1$$

$$Enabled(C) = \lambda fs . \begin{cases} \neg \text{IsEmpty}(f) \land \text{Head}(fs(f)) = X \land \text{Head}(fs(h)) = 0 \\ \lor \neg \text{IsEmpty}(f) \land \text{Head}(fs(f)) = X \land \text{Head}(fs(h)) = 1 \\ \lor \neg \text{IsEmpty}(f) \land \text{Head}(fs(f)) = Y \land \text{Head}(fs(h)) = 0 \\ \lor \neg \text{IsEmpty}(f) \land \text{Head}(fs(f)) = Y \land \text{Head}(fs(h)) = 1 \end{cases}$$

$$Consume(A) = \lambda (fs, r) . \{(fs, r)\}$$

$$Consume(B) = \lambda (fs, r) . \begin{cases} \text{if } \text{Head}(fs(g)) = 0 \\ \text{ then in}(g, B)(fs, r) \\ \text{fi} \\ \text{if } \text{Head}(fs(g)) = 1 \end{cases}$$
then \( \text{In}(g, B)(fs, r) \)

fi

\}

\text{Consume}(C) = \lambda(fs, r).

\{
  \text{if} \ \text{Head}(fs(f)) = X \land \text{Head}(fs(h)) = 0
  \text{then} \ \text{In}(f, C)(\text{In}(h, C)(fs, r))
  \text{fi},
  \text{if} \ \text{Head}(fs(f)) = X \land \text{Head}(fs(h)) = 1
  \text{then} \ \text{In}(f, C)(\text{In}(h, C)(fs, r))
  \text{fi},
  \text{if} \ \text{Head}(fs(f)) = Y \land \text{Head}(fs(h)) = 0
  \text{then} \ \text{In}(f, C)(\text{In}(h, C)(fs, r))
  \text{fi},
  \text{if} \ \text{Head}(fs(f)) = Y \land \text{Head}(fs(h)) = 1
  \text{then} \ \text{In}(f, C)(\text{In}(h, C)(fs, r))
  \text{fi}
\}

\text{Produce}(A) = \lambda(fs, r).

\{ \text{Out}(X, f, A)(\text{Out}(0, g, A)(fs, r)),
  \text{Out}(Y, f, A)(\text{Out}(1, g, A)(fs, r)) \}

\}

\text{Produce}(B) = \lambda(fs, r).

\{ \text{if} \ r(B)(g) = 0
  \text{then} \ \text{Out}(0, h, B)(fs, r)
  \text{fi},
  \text{if} \ r(B)(g) = 1
  \text{then} \ \text{Out}(0, h, B)(fs, r)
  \ \square \ \text{Out}(1, h, B)(fs, r)
  \text{fi}
\}

\text{Produce}(C) = \lambda(fs, r).
\{ \textbf{if } r(C)(f) = X \land r(C)(h) = 0 \\
\textbf{then } Out(X0, out, C)(fs, r) \\
\textbf{fi,} \\
\textbf{if } r(C)(f) = X \land r(C)(h) = 1 \\
\textbf{then } Out(X1, out, C)(fs, r) \\
\textbf{fi,} \\
\textbf{if } r(C)(f) = Y \land r(C)(h) = 0 \\
\textbf{then } Out(Y0, out, C)(fs, r) \\
\textbf{fi,} \\
\textbf{if } r(C)(f) = Y \land r(C)(h) = 1 \\
\textbf{then } Out(Y1, out, C)(fs, r) \\
\textbf{fi} \\
\}

According to Theorem (1.3.1.1), the given nf-RDFD transforms into the following marked FIFO Petri
Net \( FPN = (\{P_{FPN}, T_{FPN}, B_{FPN}, F_{FPN}, Q_{FPN}\}, M_{0,FPN}) \):
\[
P_{FPN} = \{f, g, h, \text{out}\} \cup \{A_i, A_{w:1}, B_i, B_{w:1}, B_{w:2}, C_i, C_{w:1}, C_{w:2}, C_{w:3}, C_{w:4}\} \\
T_{FPN} = \{C_{A1}, C_{B1}, C_{B2}, C_{C1}, C_{C2}, C_{C3}, C_{C4}\} \\
\cup \{P_{A1}, P_{A2}, P_{B11}, P_{B21}, P_{B22}, P_{C11}, P_{C21}, P_{C31}, P_{C41}\}
\]

The initial marking \( M_{0,FPN} \) is such that:
\[
M_{0,FPN}(A_i) = M_{0,FPN}(B_i) = M_{0,FPN}(C_i) = 1 \\
M_{0,FPN}(A_{w:1}) = M_{0,FPN}(B_{w:1}) = M_{0,FPN}(B_{w:2}) = <> \\
M_{0,FPN}(C_{w:1}) = M_{0,FPN}(C_{w:2}) = M_{0,FPN}(B_{w:3}) = M_{0,FPN}(B_{w:4}) = <> \\
M_{0,FPN}(f) = <> \\
M_{0,FPN}(g) = 0 \\
M_{0,FPN}(h) = 0 \\
M_{0,FPN}(\text{out}) = <>
\]

\( B_{FPN}, F_{FPN}, \) and \( Q_{FPN} \) can be gained from Figure 1.2. In this figure, we use a double arrow to indicate
that the forward and backward incidence mappings for a particular place/transition combination are
identical, i.e., \( B(g, C_{B1}) = F(C_{B1}, g) = 0 \). This means, that transition \( C_{B1} \) (if fired) removes the head
element (i.e., 0) of place \( g \) and appends the same element to this place. Obviously, place \( g \) always
contains only one element since it represents a persistent flow of the nf-RDFD.
1.3.2 Simulation of Program Machines by PFF–RDFD’s

**Theorem (1.3.2.1):** Every Program Machine can be simulated by an PFF–RDFD.

**Proof:** Assume we have a Program Machine with registers \( R = \{ r_1, \ldots, r_p \} \), labels \( Q = \{ q_0, \ldots, q_r \} \) and instructions \( I \). We will partially follow the proof of how to simulate a Program Machine by a FIFO Petri Net (given in [FM82] and [MF85]) when we indicate how to simulate a Program Machine by a PFF–RDFD.

We define our PFF–RDFD \( RDF_{PM} \), given in the normal form of Definition (1.2.1.7), as follows:

\[
RDF_{PM} = (B_{RDFD}, FLOWNAMES_{RDFD}, TYPES_{RDFD}, P_{RDFD}, F_{RDFD}),
\]

where

\[
B_{RDFD} = \{ q_0, \ldots, q_r \} \cup \{ r_1, \ldots, r_p \}
\]

\[
FLOWNAMES_{RDFD} = \{ \text{do}_{q_0}, \text{do}_{q_r}, \text{do}_{q_0}, \text{do}_{q_r}, \text{do}_{q_i} \mid \text{instruction labeled } q_s \text{ is an increment instruction} \}
\]

\[
\cup \bigcup_{s \in I} \{ \text{do}_{q_0}, \text{do}_{q_r}, \text{do}_{q_i} \mid \text{instruction labeled } q_s \text{ is a test and decrement instruction} \}
\]

\[
\cup \bigcup_{s \in I} \{ \text{do}_{q_0}, \text{do}_{q_r}, \text{do}_{q_i} \mid \text{instruction labeled } q_s \text{ accesses register } r_i \}
\]
$\cup \bigcup_{i=1,\ldots,r} \{next_i, act_i, val_i\}$

$\mathit{TYPES}_{RDFD} = \mathit{ENAB} \cup \mathit{ACTION} \cup \mathit{RESULT} \cup \mathit{FROM} \cup \mathit{YES} \cup \mathit{BIT}$

where $\mathit{ENAB} = \{\mathit{start, go}\}$, $\mathit{ACTION} = \{\mathit{add, sub}\}$, $\mathit{RESULT} = \{\mathit{done, iszero}\}$,

$\mathit{FROM} = \{1, \ldots, r\}$, $\mathit{YES} = \{\mathit{yes}\}$, and $\mathit{BIT} = \{0, 1\}$

$P_{RDFD} = \{\mathit{consumable}\}$

$F_{RDFD} = \{(q_0, do_{q_0}, \mathit{ENAB}, q_0, \mathit{consumable}), (q_0, do_{q_0}r_1, \mathit{ENAB}, q_1, \mathit{consumable})\}$

$\cup[\{(q_s, do_{q_s}r_m, \mathit{ENAB}, q_m, \mathit{consumable}) \mid \forall \mathit{FLOWNAMES} do_{q_s}r_m\}]$

$\cup[\{(q_s, i_{q_s}r_i, \mathit{ACTION}, r_i, \mathit{consumable}) \mid \forall \mathit{FLOWNAMES} i_{q_s}r_i\}]$

$\cup[\{(r_i, o_{r_i}q_s, \mathit{RESULT}, q_s, \mathit{consumable}) \mid \forall \mathit{FLOWNAMES} o_{r_i}q_s\}]$

$\cup \bigcup_{i=1,\ldots,r} \{(r_i, next_i, \mathit{FROM}, r_i, \mathit{consumable}),$

$(r_i, val_i, \mathit{BIT}, r_i, \mathit{consumable})\}$

We use a unary representation for nonnegative integers which are the only possible contents of the registers of the simulated Program Machine. The value 0 stands for 0 and the sequence of values $(1,\ldots,1,0)$ represents $n$. Initially, the values on the flows are $\mathit{start}$ on $do_{q_0}$ and the unary representation of the initial contents of the registers $r_1,\ldots,r_p$, i.e., the values $k_1^1,\ldots,k_1^p$ on the flows $val_1,\ldots,val_p$, respectively. All other flows are empty.

The mapping $\mathit{Enabled}$ is defined as follows:

If the bubble represents the start instruction (see Figure 1.3):

\begin{center}
\begin{tikzpicture}
    \node (q0) at (0,0) {$q_0$};
    \node (doq0) at (-1,-1) {$do_{q_0}$};
    \node (doq1) at (1,-1) {$do_{q_0}r_1$};
    \draw[->] (doq0) to (q0);
    \draw[->] (q0) to (doq1);
\end{tikzpicture}
\end{center}

Figure 1.3: Bubble $q_0$.

$\mathit{Enabled}(q_0) = \lambda s. (\neg \mathit{isEmpty}(do_{q_0}) \land \mathit{Head}(fs(do_{q_0})) = \mathit{start})$

If the instruction labeled $q_s$ is an increment instruction accessing register $r_i$ and its corresponding bubble has inflows $do_{q_m}r_i,\ldots,do_{q_m}r_j, o_{r_j}q_s$ (see Figure 1.4):

$\mathit{Enabled}(q_s) = \lambda s. \ldots$
(¬IsEmpty\(do_{q_{m-1}}, q_s\)) \land Head(fs(do_{q_{m-1}}, q_s)) = go)

\lor \ldots \lor

(¬IsEmpty\(do_{q_{m-1}}, q_s\)) \land Head(fs(do_{q_{m-1}}, q_s)) = go)

\lor (¬IsEmpty(o_{q_{m-1}}, q_s) \land Head(fs(o_{q_{m-1}}, q_s)) = done)

If the instruction labeled \(q_s\) is a test and decrement instruction accessing register \(r_i\) and its corresponding bubble has inflows \(do_{q_{m-1}}, q_s, \ldots, do_{q_{m}}, q_s, o_{q_{m-1}}, q_s\) (see Figure 1.5):

\[
\text{Enabled}(q_s) = \lambda_{fs}.
\]

(¬IsEmpty\(do_{q_{m-1}}, q_s\)) \land Head(fs(do_{q_{m-1}}, q_s)) = go)

\lor \ldots \lor

(¬IsEmpty\(do_{q_{m-1}}, q_s\)) \land Head(fs(do_{q_{m-1}}, q_s)) = go)
\[\neg\text{IsEmpty}(o_{r_i}, q_s) \land \text{Head}(fs(o_{r_i}, q_s)) = \text{done}\]
\[\neg\text{IsEmpty}(o_{r_i}, q_s) \land \text{Head}(fs(o_{r_i}, q_s)) = \text{iszero}\]

If the instruction labeled \(q_s\) is the halt instruction, i.e., \(q_s = q_f\), and its corresponding bubble has inflows \(do_{q_{m1}}, q_f, \ldots, do_{q_{m1}}, q_f\) (see Figure 1.6):

\[
\begin{align*}
& do_{q_{m1}}, q_f \\
& \vdots \\
& do_{q_{m1}}, q_f \\
\end{align*}
\]

Figure 1.6: Bubble \(q_f\).

\[\text{Enabled}(q_f) = \lambda f. \text{false}\]

If the bubble representing register \(r_i\) has inflows \(i_{\omega_1}, r_i, \ldots, i_{\omega_1}, r_i, \text{next}_i, \text{act}_i, \text{val}_i\) (see Figure 1.7):

\[\text{Enabled}(r_i) = \lambda f. \text{false}\]

These lines are required for add:

\[\neg\text{IsEmpty}(i_{\omega_1}, r_i) \land \text{Head}(fs(i_{\omega_1}, r_i)) = \text{add}\]
\[\lor \ldots \lor\]
\[\neg\text{IsEmpty}(i_{\omega_1}, r_i) \land \text{Head}(fs(i_{\omega_1}, r_i)) = \text{add}\]

These lines are required for sub:

\[\neg\text{IsEmpty}(i_{\omega_1}, r_i) \land \text{Head}(fs(i_{\omega_1}, r_i)) = \text{sub}\]
\[\land \neg\text{IsEmpty}(\text{val}_i) \land \text{Head}(fs(\text{val}_i)) = 0\]
\[\lor \ldots \lor\]
\[\neg\text{IsEmpty}(i_{\omega_1}, r_i) \land \text{Head}(fs(i_{\omega_1}, r_i)) = \text{sub}\]
\[\land \neg\text{IsEmpty}(\text{val}_i) \land \text{Head}(fs(\text{val}_i)) = 0\]
\[\lor \ldots \lor\]
\[\neg\text{IsEmpty}(i_{\omega_1}, r_i) \land \text{Head}(fs(i_{\omega_1}, r_i)) = \text{sub}\]
\[\land \neg\text{IsEmpty}(\text{val}_i) \land \text{Head}(fs(\text{val}_i)) = 1\]
\[\lor \ldots \lor\]
\[\neg\text{IsEmpty}(i_{\omega_1}, r_i) \land \text{Head}(fs(i_{\omega_1}, r_i)) = \text{sub}\]
\[\land \neg\text{IsEmpty}(\text{val}_i) \land \text{Head}(fs(\text{val}_i)) = 1\]

This line is required to copy the tail of 1’s:

\[\neg\text{IsEmpty}(\text{act}_i) \land \text{Head}(fs(\text{act}_i)) = \text{yes}\]
\[\land \neg\text{IsEmpty}(\text{val}_i) \land \text{Head}(fs(\text{val}_i)) = 1\]

These lines are required to activate the next instruction:
\(\forall (\neg IsEmpty(act_i) \land Head(fs(act_i))) = yes\)
\[\land \neg IsEmpty(val_i) \land Head(fs(val_i)) = 0\]
\[\land \neg IsEmpty(next_i) \land Head(fs(next_i)) = s_i\]
\(\forall \ldots \forall\)
\((-IsEmpty(act_i) \land Head(fs(act_i))) = yes\)
\[\land \neg IsEmpty(val_i) \land Head(fs(val_i)) = 0\]
\[\land \neg IsEmpty(next_i) \land Head(fs(next_i)) = s_i\]

\[\text{Figure 1.7: Bubble } r_i.\]

As usual, we assume that whenever a set of input conditions on flows enables a bubble, all the head elements on these flows will be consumed when this bubble actually goes from idle to working. Therefore, we omit to list the mapping Consume. We immediately continue with Produce.

If the bubble represents the start instruction (see Figure 1.3):

\[
Produce(q_0) = \lambda(fs, r).
\]

\[
\{\text{if } r(q_0)(do, q_0) = \text{start}\]
\[
\text{then } Out(go, do, q_0 + q_1, q_0)(fs, r)
\]
\[
\text{fi}
\]

If the instruction labeled \(q_s\) is an increment instruction accessing register \(r_i\) and its corresponding bubble has inflows \(do, q_s, \ldots, do, q_m, \omega_s, \omega_s, \) and outflows \(do, q_s, \omega_s, i, \omega_s, \omega_s\) (see Figure 1.4):
Produce\((q_s) = \lambda(fs, r)\).

\[
\begin{align*}
\{ & \text{if } r(q_s)(do_{\omega/m}, \omega_s) = go \\
& \text{then } Out(add, i_{\omega_s, \omega^i_s}, q_s)(fs, r) \\
& \text{fi,} \\
& \ldots, \\
& \text{if } r(q_s)(do_{\omega/m}, \omega_s) = go \\
& \text{then } Out(add, i_{\omega_s, \omega^i_s}, q_s)(fs, r) \\
& \text{fi,} \\
& \text{if } r(q_s)(o_{\omega^i_s, \omega_s}) = done \\
& \text{then } Out(go, do_{\omega_s, \omega[l], q_s})(fs, r) \\
& \text{fi}
\}
\]

If the instruction labeled \(q_s\) is a test and decrement instruction accessing register \(r_i\) and its corresponding bubble has inflows \(do_{\omega/s}, \omega_s, \ldots, do_{\omega/m}, \omega_s, o_{\omega^i, \omega^i_s}\) and outflows \(do_{\omega/s}, \omega[l], q_s, \omega[l], \omega^i_s\) (see Figure 1.5):

\[
\begin{align*}
\{ & \text{if } r(q_s)(do_{\omega/m}, \omega_s) = go \\
& \text{then } Out(sub, i_{\omega_s, \omega^i_s}, q_s)(fs, r) \\
& \text{fi,} \\
& \ldots, \\
& \text{if } r(q_s)(do_{\omega/m}, \omega_s) = go \\
& \text{then } Out(sub, i_{\omega_s, \omega^i_s}, q_s)(fs, r) \\
& \text{fi,} \\
& \text{if } r(q_s)(o_{\omega^i_s, \omega_s}) = done \\
& \text{then } Out(go, do_{\omega_s, \omega[l], q_s})(fs, r) \\
& \text{fi,} \\
& \text{if } r(q_s)(o_{\omega^i_s, \omega_s}) = iszero \\
& \text{then } Out(go, do_{\omega_s, \omega[l], q_s})(fs, r) \\
& \text{fi}
\}
\]

The next line is given only for formal reasons, but it will never be executed since the corresponding enabling condition is always false. If the instruction labeled \(q_s\) is the halt instruction, i.e., \(q_s = q_f\),
and its corresponding bubble has inflows \(do_{q_l, q_f}, \ldots, do_{q_{m-1}, q_f}\) (see Figure 1.6):

\[
Produce(q_f) = \lambda(fs, r) \cdot \{(fs, [q_f \mapsto \lambda f . \perp r])
\]

If the bubble representing register \(r_i\) has inflows \(i_{\omega_{j_i}} \cdot r_i, \ldots, i_{\omega_{j_i}} \cdot r_i, next_i, act_i, val_i\) and outflows \(o_{\omega_{j_i}} \cdot s_i, \ldots, o_{\omega_{j_i}} \cdot s_i, next_i, act_i, val_i\) (see Figure 1.7):

\[
Produce(r_i) = \lambda(fs, r).
\]

[These lines are required for add:]

\[
\begin{align*}
& \text{if } r(r_i)(i_{\omega_{j_i}} r_i) = add \\
& \text{then } Out(s_i, next_i, r_i)(Out(yes, act_i, r_i)(Out(1, val_i, r_i)(fs, r))) \\
& \text{fi}, \\
& \ldots, \\
& \text{if } r(r_i)(i_{\omega_{j_i}} r_i) = add \\
& \text{then } Out(s_i, next_i, r_i)(Out(yes, act_i, r_i)(Out(1, val_i, r_i)(fs, r))) \\
& \text{fi},
\end{align*}
\]

[These lines are required for sub:]

\[
\begin{align*}
& \text{if } r(r_i)(i_{\omega_{j_i}} r_i) = sub \land r(r_i)(val_i) = 0 \\
& \text{then } Out(0, val_i, r_i)(Out(iszero, o_{\omega_{j_i}} s_i, r_i)(fs, r)) \\
& \text{fi}, \\
& \ldots, \\
& \text{if } r(r_i)(i_{\omega_{j_i}} r_i) = sub \land r(r_i)(val_i) = 0 \\
& \text{then } Out(0, val_i, r_i)(Out(iszero, o_{\omega_{j_i}} s_i, r_i)(fs, r)) \\
& \text{fi}, \\
& \text{if } r(r_i)(i_{\omega_{j_i}} r_i) = sub \land r(r_i)(val_i) = 1 \\
& \text{then } Out(s_i, next_i, r_i)(Out(yes, act_i, r_i)(fs, r)) \\
& \text{fi}, \\
& \ldots, \\
& \text{if } r(r_i)(i_{\omega_{j_i}} r_i) = sub \land r(r_i)(val_i) = 1 \\
& \text{then } Out(s_i, next_i, r_i)(Out(yes, act_i, r_i)(fs, r)) \\
& \text{fi},
\end{align*}
\]

[This line is required to copy the tail of 1's:]

\[
\begin{align*}
& \text{if } r(r_i)(act_i) = yes \land r(r_i)(val_i) = 1 \\
& \text{then } Out(yes, act_i, r_i)(Out(1, val_i, r_i)(fs, r)) \\
& \text{fi},
\end{align*}
\]
These lines are required to activate the next instruction:

\[
\text{if } r(r_i)(act_i) = \text{yes} \land r(r_i)(val_i) = 0 \land r(r_i)(next_i) = s_i \\
\text{then } Out(0, val_i, r_i)(Out(done, o_f; q_{s1}, r_i)(f_s, r)) \\
\text{fi,}
\]

\[
\ldots,
\]

\[
\text{if } r(r_i)(act_i) = \text{yes} \land r(r_i)(val_i) = 0 \land r(r_i)(next_i) = s_i \\
\text{then } Out(0, val_i, r_i)(Out(done, o_f; q_{s1}, r_i)(f_s, r)) \\
\text{fi}
\]

Example (1.3.2.2): Consider a Program Machine that initially has some nonnegative values in its registers \(r_1\) and \(r_2\), while \(r_3\) contains 0. The following code stores the sum of \(r_1\) and \(r_2\) in \(r_3\) and erases the original values:

\[
q_0 : \text{start goto } q_1;
\]

\[
q_1 : \text{if } r_1 = 0 \text{ then goto } q_3 \text{ else } r_1 := r_1 - 1 \text{ goto } q_2;
\]

\[
q_2 : r_3 := r_3 + 1 \text{ goto } q_1;
\]

\[
q_3 : \text{if } r_2 = 0 \text{ then goto } q_f \text{ else } r_2 := r_2 - 1 \text{ goto } q_4;
\]

\[
q_4 : r_3 := r_3 + 1 \text{ goto } q_3;
\]

\[
q_f : \text{halt.}
\]

The mapping \(\text{Enabled}\) is defined as follows:

\[
\text{Enabled}(q_0) = \lambda s_0.
\]

The graphical representation of the equivalent PFF-RFD is given in Figure 1.8.

Based on this diagram, the formal definitions can be gained according to Theorem (1.3.2.1) as:

\[
B_{RFD} = \{ q_0, q_1, q_2, q_3, q_4, q_f \} \cup \{ r_1, r_2, r_3 \}
\]

\[
FLONAMES_{RFD} = \{ do_{q_0}, do_{q_1}, q_1 \}
\]

\[
\cup \{ do_{q_2}, do_{q_3}, do_{q_4}, q_f \}
\]

\[
\cup \{ i_{q_1}, o_{q_1}, i_{q_2}, o_{q_2}, i_{q_3}, o_{q_3}, i_{q_4}, o_{q_4} \}
\]

\[
\cup \{ next_1, act_1, val_1, next_2, act_2, val_2, next_3, act_3, val_3 \}
\]

\[
TYPES_{RFD} \text{ (with FROM } = \{ 1, 2, 3, 4 \} \text{), } P_{RFD}, \text{ and } F_{RFD} \text{ follow immediately.}
\]

Assume we want to add 2 and 3, then the initial values, i.e., sequences of values, on the flows are \(do_{q_0} = \text{start}, val_1 = (1, 1, 0), val_2 = (1, 1, 1, 0)\) and \(val_3 = 0\). All other flows are empty.

The mapping \(\text{Enabled}\) is defined as follows:

\[
\text{Enabled}(q_0) = \lambda s_0.
\]
Figure 1.8: PFF-RFD.

\(-Is\,Empty(do_{q_0}) \land Head(fs(do_{q_0})) = \text{start}\)

\(Enabled(q_1) = \lambda s .\)

\((-Is\,Empty(do_{q_1}) \land Head(fs(do_{q_1})) = \text{go}\)\)

\(\forall(-Is\,Empty(do_{q_2}) \land Head(fs(do_{q_2})) = \text{go}\)\)
\(\forall (-\text{IsEmpty}(o_{\omega 1, q_1}) \land \text{Head}(fs(o_{\omega 1, q_1})) = \text{done})\)

\(\forall (-\text{IsEmpty}(o_{\omega 1, q_1}) \land \text{Head}(fs(o_{\omega 1, q_1})) = \text{iszero})\)

\(\text{Enabled}(q_2) = \lambda f s .\)

\((-\text{IsEmpty}(do_{\omega 1, q_2}) \land \text{Head}(fs(do_{\omega 1, q_2})) = \text{go})\)

\(\forall (-\text{IsEmpty}(o_{\omega 3, q_2}) \land \text{Head}(fs(o_{\omega 3, q_2})) = \text{done})\)

\(\text{Enabled}(q_3) = \lambda f s .\)

\((-\text{IsEmpty}(do_{\omega 3, q_3}) \land \text{Head}(fs(do_{\omega 3, q_3})) = \text{go})\)

\(\forall (-\text{IsEmpty}(o_{\omega 3, q_3}) \land \text{Head}(fs(o_{\omega 3, q_3})) = \text{iszero})\)

\(\text{Enabled}(q_4) = \lambda f s .\)

\((-\text{IsEmpty}(do_{\omega 3, q_4}) \land \text{Head}(fs(do_{\omega 3, q_4})) = \text{go})\)

\(\forall (-\text{IsEmpty}(o_{\omega 3, q_4}) \land \text{Head}(fs(o_{\omega 3, q_4})) = \text{done})\)

\(\text{Enabled}(q_5) = \lambda f s . \text{false}\)

\(\text{Enabled}(r_1) = \lambda f s .\)

\((-\text{IsEmpty}(i_{\omega 1, r_1}) \land \text{Head}(fs(i_{\omega 1, r_1})) = \text{add})\)

\(\forall (-\text{IsEmpty}(i_{\omega 1, r_1}) \land \text{Head}(fs(i_{\omega 1, r_1})) = \text{sub})\)

\(-\text{IsEmpty}(val_1) \land \text{Head}(fs(val_1)) = 0\)

\(\forall (-\text{IsEmpty}(val_1) \land \text{Head}(fs(val_1)) = 1)\)

\((-\text{IsEmpty}(act_1) \land \text{Head}(fs(act_1)) = \text{yes})\)

\(-\text{IsEmpty}(val_1) \land \text{Head}(fs(val_1)) = 1\)

\(\forall (-\text{IsEmpty}(act_1) \land \text{Head}(fs(act_1)) = \text{yes})\)

\(-\text{IsEmpty}(val_1) \land \text{Head}(fs(val_1)) = 0\)

\(-\text{IsEmpty}(next_1) \land \text{Head}(fs(next_1)) = 1\)

\(\text{Enabled}(r_2) = \lambda f s .\)

\((-\text{IsEmpty}(i_{\omega 3, r_2}) \land \text{Head}(fs(i_{\omega 3, r_2})) = \text{add})\)

\(\forall (-\text{IsEmpty}(i_{\omega 3, r_2}) \land \text{Head}(fs(i_{\omega 3, r_2})) = \text{sub})\)

\(-\text{IsEmpty}(val_2) \land \text{Head}(fs(val_2)) = 0\)

\(\forall (-\text{IsEmpty}(val_2) \land \text{Head}(fs(val_2)) = 1)\)

\(-\text{IsEmpty}(act_2) \land \text{Head}(fs(act_2)) = \text{yes}\)
\(\neg \text{IsEmpty}(val_2) \land \text{Head}(fs(val_2)) = 1\)

\(\forall (\neg \text{IsEmpty}(act_2) \land \text{Head}(fs(act_2)) = \text{yes}\)

\(\neg \text{IsEmpty}(val_2) \land \text{Head}(fs(val_2)) = 0\)

\(\forall (\neg \text{IsEmpty}(next_2) \land \text{Head}(fs(next_2)) = 3)\)

\(\text{Enabled}(r_3) = \lambda f s .\)

\((\neg \text{IsEmpty}(i.q_2 .r_3) \land \text{Head}(fs(i.q_2 .r_3)) = \text{add}\)

\(\forall (\neg \text{IsEmpty}(i.q_4 .r_3) \land \text{Head}(fs(i.q_4 .r_3)) = \text{add}\)

\(\forall (\neg \text{IsEmpty}(i.q_2 .r_3) \land \text{Head}(fs(i.q_2 .r_3)) = \text{sub}\)

\(\neg \text{IsEmpty}(val_3) \land \text{Head}(fs(val_3)) = 0\)

\(\forall (\neg \text{IsEmpty}(i.q_4 .r_3) \land \text{Head}(fs(i.q_4 .r_3)) = \text{sub}\)

\(\neg \text{IsEmpty}(val_3) \land \text{Head}(fs(val_3)) = 0\)

\(\forall (\neg \text{IsEmpty}(i.q_2 .r_3) \land \text{Head}(fs(i.q_2 .r_3)) = \text{sub}\)

\(\neg \text{IsEmpty}(val_3) \land \text{Head}(fs(val_3)) = 1\)

\(\forall (\neg \text{IsEmpty}(i.q_4 .r_3) \land \text{Head}(fs(i.q_4 .r_3)) = \text{sub}\)

\(\neg \text{IsEmpty}(val_3) \land \text{Head}(fs(val_3)) = 1\)

\(\forall (\neg \text{IsEmpty}(act_3) \land \text{Head}(fs(act_3)) = \text{yes}\)

\(\neg \text{IsEmpty}(val_3) \land \text{Head}(fs(val_3)) = 1\)

\(\forall (\neg \text{IsEmpty}(act_3) \land \text{Head}(fs(act_3)) = \text{yes}\)

\(\neg \text{IsEmpty}(val_3) \land \text{Head}(fs(val_3)) = 0\)

\(\forall (\neg \text{IsEmpty}(next_3) \land \text{Head}(fs(next_3)) = 2\)

\(\forall (\neg \text{IsEmpty}(act_3) \land \text{Head}(fs(act_3)) = \text{yes}\)

\(\neg \text{IsEmpty}(val_3) \land \text{Head}(fs(val_3)) = 0\)

\(\forall (\neg \text{IsEmpty}(next_3) \land \text{Head}(fs(next_3)) = 4\)

As usual, we assume that whenever a set of input conditions on flows enables a bubble, all the head elements on these flows will be consumed when this bubble actually goes from idle to working. Therefore, we omit to list the mapping Consumes. We immediately continue with the mapping Produce.

\(\text{Produce}(q_0) = \lambda f s, r.\)

\(\{\text{if } r(q_0)(do_0 q_0) = \text{start}\)

\(\text{then } \text{Out}(go, do_0 q_0 .q_1, q_0)(f s, r)\)

\(\text{fi}\)

\}

\(\text{Produce}(q_1) = \lambda f s, r.\)
\{if r(q_1)(do \cdot q_0, q_1) = go \\
then \text{Out}(\text{sub}, i \cdot q_1, q_1)(fs, r) \\
fi, \\
if r(q_1)(do \cdot q_2, q_1) = go \\
then \text{Out}(\text{sub}, i \cdot q_1, q_1)(fs, r) \\
fi, \\
if r(q_1)(o \cdot q_1, q_1) = done \\
then \text{Out}(go, do \cdot q_1, q_1)(fs, r) \\
fi, \\
if r(q_1)(o \cdot q_1, q_1) = iszero \\
then \text{Out}(go, do \cdot q_1, q_3, q_1)(fs, r) \\
fi \}

\text{Produce}(q_2) = \lambda (fs, r) . \\
\{if r(q_2)(do \cdot q_1, q_2) = go \\
then \text{Out}(\text{add}, i \cdot q_2, q_3, q_2)(fs, r) \\
fi, \\
if r(q_2)(o \cdot q_3, q_2) = done \\
then \text{Out}(go, do \cdot q_1, q_2, q_3)(fs, r) \\
fi \}

\text{Produce}(q_3) = \lambda (fs, r) . \\
\{if r(q_3)(do \cdot q_1, q_3) = go \\
then \text{Out}(\text{sub}, i \cdot q_3, q_2, q_3)(fs, r) \\
fi, \\
if r(q_3)(do \cdot q_4, q_3) = go \\
then \text{Out}(\text{sub}, i \cdot q_3, q_2, q_3)(fs, r) \\
fi, \\
if r(q_3)(o \cdot q_2, q_3) = done \\
then \text{Out}(go, do \cdot q_3, q_2, q_3)(fs, r) \\
fi, \\
if r(q_3)(o \cdot q_2, q_3) = iszero \\
then \text{Produce}(q_3)(fs, r) = \lambda (fs, r) .
then $Out(go, do_{\omega_1 \omega_3}, q_3)(fs, r)$

fi

}

$Produce(q_4) = \lambda (fs, r) \cdot$

{if $r(q_4)(do_{\omega_3}, q_4) = go$

then $Out(add, i_{\omega_4 \omega_3}, q_4)(fs, r)$

fi,

if $r(q_4)(o_{\omega_3}, q_4) = done$

then $Out(go, do_{\omega_4 \omega_3}, q_4)(fs, r)$

fi

}

$Produce(q_f) = \lambda (fs, r) \cdot \{(fs, [q_f \mapsto \lambda f . \bot] r)\}$

$Produce(r_1) = \lambda (fs, r) \cdot$

{if $r(r_1)((i_{\omega_1} \omega_1) r_1) = add$

then $Out(1, next_1, r_1)(Out(yes, act_1, r_1)(Out(1, val_1, r_1)(fs, r)))$

fi,

if $r(r_1)((i_{\omega_1} \omega_1) r_1) = sub \land r(r_1)(val_1) = 0$

then $Out(0, val_1, r_1)(Out(iszero, o_{\omega_1 \omega_1}, r_1)(fs, r))$

fi,

if $r(r_1)((i_{\omega_1} \omega_1) r_1) = sub \land r(r_1)(val_1) = 1$

then $Out(1, next_1, r_1)(Out(yes, act_1, r_1)(fs, r))$

fi,

if $r(r_1)(act_1) = yes \land r(r_1)(val_1) = 1$

then $Out(yes, act_1, r_1)(Out(1, val_1, r_1)(fs, r))$

fi,

if $r(r_1)(act_1) = yes \land r(r_1)(val_1) = 0 \land r(r_1)(next_1) = 1$

then $Out(0, val_1, r_1)(Out(done, o_{\omega_1 \omega_1}, r_1)(fs, r))$

fi

}

$Produce(r_2) = \lambda (fs, r) \cdot$

{if $r(r_2)((i_{\omega_2} \omega_2) r_2) = add$

then $Out(3, next_2, r_2)(Out(yes, act_2, r_2)(Out(1, val_2, r_2)(fs, r)))$
\( \text{Produce}(r_3) = \lambda(fs, r). \)

\[
\begin{align*}
&\text{if } r(r_3)(i_{\omega_2}r_3) = \text{sub} \land r(r_3)(val_3) = 0 \\
&\text{then } Out(0, val_3, r_3)(Out(is\ zero, o_{\omega_2}q_3, r_2)(fs, r)) \\
&\text{fi,} \\
&\text{if } r(r_3)(i_{\omega_2}r_3) = \text{sub} \land r(r_3)(val_3) = 1 \\
&\text{then } Out(3, next_2, r_2)(Out(yes, act_2, r_2)(fs, r)) \\
&\text{fi,} \\
&\text{if } r(r_3)(act_2) = yes \land r(r_3)(val_3) = 1 \\
&\text{then } Out(yes, act_2, r_2)(Out(1, val_2, r_2)(fs, r)) \\
&\text{fi,} \\
&\text{if } r(r_3)(act_2) = yes \land r(r_3)(val_3) = 0 \land r(r_3)(next_2) = 3 \\
&\text{then } Out(0, val_2, r_2)(Out(done, o_{\omega_2}q_3, r_2)(fs, r)) \\
&\text{fi}
\end{align*}
\]
\[ \begin{align*}
\text{\texttt{if}} & \quad r(r_3)(act_3) = yes \wedge r(r_3)(val_3) = 1 \\
\text{\texttt{then}} & \quad Out(yes, \text{\texttt{act}}_3, r_3)(Out(1, val_3, r_3)(fs, r)) \\
\text{\texttt{fi}},
\end{align*} \]

\[ \begin{align*}
\text{\texttt{if}} & \quad r(r_3)(act_3) = yes \wedge r(r_3)(val_3) = 0 \wedge r(r_3)(next_3) = 2 \\
\text{\texttt{then}} & \quad Out(0, val_3, r_3)(Out(done, a_3.q_2, r_3)(fs, r)) \\
\text{\texttt{fi}},
\end{align*} \]

\[ \begin{align*}
\text{\texttt{if}} & \quad r(r_3)(act_3) = yes \wedge r(r_3)(val_3) = 0 \wedge r(r_3)(next_3) = 4 \\
\text{\texttt{then}} & \quad Out(0, val_3, r_3)(Out(done, a_3.q_4, r_3)(fs, r)) \\
\text{\texttt{fi}}
\end{align*} \]

1.4 Summary

In this paper, we have shown that PFF–RDFD’s have the computational power of Turing Machines. Therefore, all interesting decidability problems such as reachability, termination, deadlock and liveness properties, and finiteness, that are undecidable for Turing Machines are undecidable for PFF–RDFD’s, too.

Future work will have two directions: (i) simulation of FDFD’s that make use of persistent flows, stores, infinite domains for flow values, and the facility for testing for empty flows through PFF–RDFD’s and (ii) further restrictions on RDFD’s. Direction (i) should help to provide a mechanism such that existing FDFD’s can be transformed into a basic model. Then, such a model might be used as input to computer software for formal analysis and execution of FDFD’s such as the ML interpreter described in [Wah95].

In direction (ii), we hope to find subclasses of RDFD’s where some decidability problems can be solved. In particular, we would like to show that some of these subclasses can be simulated by Monogeneous FIFO Petri Nets, Linear FIFO Petri Nets, and Topologically Free Choice FIFO Petri Nets, respectively, and that this simulation is still based on an isomorphism. Then, since this type of a homomorphism preserves some decidability problems ([KM82]), we could immediately apply the results and algorithms known for a subclass of FIFO Petri Nets ([FM82], [MF85], [Fin86], [Rou87], [FC88], [FR88], to mention only a few) to the corresponding subclass of RDFD’s.
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